

# Jihoon Hong

+1-470-667-7557 | [jhong392@gatech.edu](mailto:jhong392@gatech.edu) | <https://athlon76.github.io/>

 Jihoon Hong |  athlon76

Atlanta, GA

## RESEARCH INTERESTS

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Uncertainty-aware computer vision techniques and control-theoretic tools for robust, reliable, and safe learning-enabled robotic systems, with applications in safe navigation and constrained generation.

## EDUCATION

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- **Georgia Institute of Technology** Aug. 2024 - Expected Aug. 2029  
*Ph.D., Machine Learning* Atlanta, GA
- **Seoul National University** Mar. 2017 - Feb. 2024  
*B.A., Economics & B.S., Computer Science and Engineering* Seoul, Korea
  - *Summa Cum Laude* (GPA: 3.93/4.0)
  - Minor in Mathematics

## RESEARCH EXPERIENCE

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- **Verifiable Optimization for Imaging and Learning Advances (VOILA) Lab** May 2025 - Present  
*Advised by Dr. Sara Fridovich-Keil* Atlanta, GA
  - Developing uncertainty quantification and out-of-distribution detection methods using diffusion priors.
- **Trustworthy Robotics Lab** May 2025 - Present  
*Advised by Dr. Glen Chou* Atlanta, GA
  - Improving robustness and performance of world/action models via control-theoretic analysis and intervention.

## PUBLICATIONS

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C=CONFERENCE, J=JOURNAL, U=UNDER REVIEW

\* denotes equal contribution.

- [J.1] J. Hong, C. Chiu, S. Fridovich-Keil, G. Chou. (2026). **PolyMerge: Compressing 3D Gaussian Splats with Polytope Coverings for Provably Safe Resource-Constrained Navigation**. *IEEE Robotics and Automation Letters (RA-L)*. DOI: 10.1109/LRA.2026.3692083
- [C.3] A. Kheirandish\*, J. Hong\*, S. Fridovich-Keil. (2026). **KLIP: localized distribution shift detection via KL-divergence with diffusion priors in Inverse Problems**. *IEEE/CVF Conference on Computer Vision and Pattern Recognition (CVPR)*, 2026.
- [C.2] S. Lee, H. Lee, J. Hong, S. Cho, J. Lee. (2024). **VGA: Hardware Accelerator for Scalable Long Sequence Model**. *57<sup>th</sup> International Symposium on Microarchitecture (MICRO)*.
- [C.1] H. Lee, J. Hong, S. Kim, S. Lee, J. Lee. (2023). **A Memory-Efficient Edge Inference Accelerator with XOR-based Model Compression**. *60<sup>th</sup> Design Automation Conference (DAC)*.
- [U.3] J. Hong, J. Skifstad, Q. Dai, A. Chan, G. Chou. (2026). **Steering Robustness into World Action Models via Mechanistic Interpretability and Optimal Control**. Manuscript submitted to the *Conference on Robot Learning (CoRL)*.
- [U.2] J. Hong, A. Chan, Q. Dai, J. Skifstad, G. Chou. (2026). **Activation Steering of Video Generation Models via Reduced-Order Linear Optimal Control**. Manuscript submitted to the *40<sup>th</sup> Annual Conference on Neural Information Processing Systems (NeurIPS)*.
- [U.1] J. Hong\*, A. Kheirandish\*, S. Fridovich-Keil. (2026). **LACToS: Local Anomaly detection via Conditional Typicality of Superpixels**. Manuscript submitted to the *40<sup>th</sup> Annual Conference on Neural Information Processing Systems (NeurIPS)*.

## HONORS AND AWARDS

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- **Kwanjeong Educational Foundation (KEF) Scholarship** Sep. 2024 – Aug. 2029